CCAT

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Why CCAT?

CCAT
25 m, 10 μm rms
Cerro Chajnantor
CCAT Overview

- **Big**: 25 m diameter submm telescope
  - high aperture efficiency at 200 μm
- **Wide**: Field of View > 15’
  - large format bolometer array cameras
- **High**: dry, tropical mountain site
  - 5600 m, median PVW < 1 mm
  - wide sky coverage
- **Complement**: ALMA
CCAT Science Strengths

- Past decade: submillimeter astronomy is important!!
- CCAT:
  - Large and sensitive
  - Designed for wide-field imaging
  - Wide spectral coverage
  - Excellent performance at 350 μm
    - site, surface
  - 3.5" resolution @ 350 μm
  - Multicolor information (SED)
  - Study high z tail of CIB sources
- CCAT will complement ALMA
  - Fast continuum mapping vs. high angular & spectral resolution
  - Comparable sensitivities: identify targets for ALMA
- Clusters (SZ), submm galaxies, star-forming regions & cores, debris disks, KBOs
Continuum sensitivities of CCAT and other instruments (5 $\sigma$ in 1 hour) with confusion limits (30 beams source$^{-1}$). CCAT sensitivities computed for precipitable water vapor appropriate to that band.
Submm Galaxy Detection Rate

• CCAT is an ultrafast mapper
• Assumptions
  – 32 x 32 (1024) pixel detector, Nyquist sampled, 350 μm & 850 μm
  – Observationally verified counts (good to factor 2)
  – Confusion and all sky limits
• 350 μm & 850 μm detection rates are compatible, but
• Confusion at 350 μm is deeper than at 850 μm
• Detection rates:
  – ~150 x SCUBA2; ~300 x ALMA
  – About 100-6000 per hour
  – Lifetime detection of order 10^7-8 galaxies: ~1% of ALL galaxies!
• ‘1/3 sky survey’: ~1000 deg^2 at 3 deg^2 hr^{-1} in 5000 hr
Distant Submm Galaxy Surveys

• CCAT Detection Rate Will Provides Huge Samples
  – Find rare distant red objects; i.e., opt/IR (or 350 μm) dropouts
  – Address clustering properties of submm galaxies
  – Map large scale structure, high density regions
  – Measure submm galaxy luminosity function

• CCAT Confusion Limit Fainter than Other Surveys
  – Higher precision number counts
  – Are faint submm galaxies more quiescent?

• Surveys Guide Detailed Follow-on Studies with ALMA
  – CCAT will provide accurate positions
Images of the Antennae show the submillimeter reveals active star formation regions hidden at shorter wavelengths. The bulk of the luminosity emerges in the submillimeter. CCAT will provide a submillimeter image with a spatial resolution similar to the infrared image. Mapping this galaxy would require hundreds of pointings with ALMA. With CCAT’s high mapping speed and sensitivity, a complete survey of all galaxies in the local volume would be practical.
CCAT Galactic Plane Survey

- Measure the Galaxy-wide star formation rate and history
- Obtain the complete inventory of cold dust in the Galactic Plane
- Determine the relative importance of global and local triggers for star formation
- Provide templates, recipes and prescriptions for Xgal science

CCAT mapping speed (0.9 deg$^2$ hr$^{-1}$) and sensitivity (8.5 mJy) enable:
  - a complete survey of the “inner” Galactic Plane
  - detect \textit{all} star forming regions (i.e., cool dust)
  - not just massive star regions (i.e., warm or hot dust)
Debris Disks with CCAT

- Debris disks, a.k.a. "Vega phenomenon", a.k.a. "extra-zodiacal dust":
  - solid particles around main sequence stars, especially younger ones (10-100 Myr); gas has been absorbed into giant planets or expelled
  - Produced by collisional grinding of planetesimals in Kuiper belts; probably episodic
  - trace orbital dynamics (analogous to Saturn’s rings)

- CCAT objectives
  - high-quality images of statistical sample of nearby disk systems
  - surveys for undiscovered cold disks ($T < 40$ K) around nearby stars
  - important data points on spectral energy distribution
    - characteristics of particles $\Rightarrow$ evolutionary clues?
    - much better measurement of mass than is possible with scattered light images
  - unbiased surveys for disks in stellar clusters

\[\beta\] Pictoris: debris disk discovery image
Smith & Terrile (1984)
Images of Fomalhaut debris disk at 350 μm. The observed image (left), with 10″ resolution, shows a complete debris ring encircling the star. With enhanced (3″) resolution (right), we can infer the presence of a planet due to the asymmetry of the ring. CCAT will achieve this resolution intrinsically and be capable of 1″ resolution with image enhancement techniques. CCAT imaging will measure the entire flux and should show substructure pinpointing the location of the planet. Imaging this system would require dozens of ACA pointings.
KBO submm advantage

Optical brightness (refl.)

\[ B \propto R^{-4} \]

Submm flux (thermal)

\[ S \propto R^{-5/2} \]

Submm advantage

\[ \propto R^{+3/2} \]

Predicted 350 μm flux for KBOs with 4% albedo (\( m_R = 23 \), solid, and \( m_R = 24 \), dotted). Horizontal lines show the 5 \( \sigma \) detection limits for one and two hour observations, respectively, with CCAT.
<table>
<thead>
<tr>
<th>Requirement</th>
<th>Goal</th>
<th>remark</th>
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</thead>
<tbody>
<tr>
<td>Wavelength</td>
<td>350 – 1400</td>
<td>200 – 2500 μm</td>
</tr>
<tr>
<td>Aperture</td>
<td>25 m</td>
<td></td>
</tr>
<tr>
<td>Field of view</td>
<td>10'</td>
<td>20'</td>
</tr>
<tr>
<td>Half WFE</td>
<td>&lt; 12.5 μm</td>
<td>&lt; 9.5 μm rms</td>
</tr>
<tr>
<td>Site condns.</td>
<td>&lt; 1.0 mm</td>
<td>&lt; 0.7 mm median pwv</td>
</tr>
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These Goals and Advanced Bolometer Arrays Will Make CCAT a Revolutionary New Observatory
CCAT Concept Design

- RC Optics, Nasmyth Foci
- Calotte Dome
  - Internal storm shutter
- High Performance Mount
  - Precise pointing, 0.3" rms
  - Agile scanning motions
- Active Primary Surface
  - Kinematic panel supports
  - Closed loop control
  - Holography alignment
- Cerro Chajnantor, 5612 m
  - Instrument prep. & ops. areas
  - Oxygen enrichment in rooms
- Base Facility near San Pedro
Atmospheric Transmission

ATM 2002 Model (Pardo et al.)

<table>
<thead>
<tr>
<th></th>
<th>CCAT 10%</th>
<th>CCAT 25%</th>
<th>CCAT 50%</th>
<th>ALMA 50%</th>
<th>CSO 50%</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature</td>
<td>273 K</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PWV</td>
<td>5600 m</td>
<td></td>
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<tr>
<td>Transmission</td>
<td></td>
<td></td>
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<tr>
<td>Frequency [GHz]</td>
<td>0.5</td>
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- CCAT 10% 5600 m 150 μm
- CCAT 25% 5600 m 400 μm
- CCAT 50% 5600 m 700 μm
- ALMA 50% 5000 m 1000 μm
- CSO 50% 4100 m 2000 μm
View of Northern Chile (NASA Space Shuttle)

ESO PR Photo 24b/99 (8 June 1999)

© ESO - ESA - Claude Niccolier
Cerro Chajnantor 5612 m

View SW from ASTE; access road constructed by U. Tokyo
Cerro Chajnantor 5612 m

CCAT equipment overlooking ASTE & NANTEN2 @ 4800 m
Better 350 μm Transparency

- Two Tippers: CCAT (5600 m) & CBI (5050 m)
- Side-by-Side at CBI: Same Values
- Better Transparency at CCAT
- Less Water Vapor at CCAT
  - $\tau_{\text{off}} \approx 0.5$
  - Slope $\propto$ PVW
  - $\text{PWV(CCAT)} \leq 70\% \text{ PWV(CBI)}$
Optical Design

- **Ritchey Chretién Layout**
  - Wide field of view
  - High Strehl ratio
  - High aperture efficiency

- **f 0.4 Primary Focus**
  - Compact telescope
  - Minimum dome
  - Monolithic secondary mirror

- **f 8 Secondary Focus**
  - Match instruments

- **Nasmyth Foci**
  - Rapid instrument changes
  - Large cameras

- **Bent Cassegrain Foci**
  - Diagnostic instruments
  - Small instruments
Facility Concept Design
M3 Engineering & Technology

- Summit Facility
- Minimum Size
  - Support Operations
- Oxygen Enrichment
  - Working Areas at Summit

- Base Facility
- Road and Site
Calotte Dome Concept

- 42 m Diameter
- 28 m Aperture
- Secondary Mirror Inside
- Two Rotation Stages
  - Tilted stage: tech. challenge
- Better Wind Protection
- Less Drive Power
- Internal Closure
- Similar to TMT design
- (AMEC) Dynamic Struct.
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- AMEC Dynamic Struct.
CCAT Mount

- Combines Radio and Optical Telescopes Approaches
- Hydrostatic (Az) & Rolling Element (EI) Bearings
- Vertex RSI Dallas (GD)

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<tr>
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<tr>
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<td>0.01 deg/sec²</td>
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Primary Mirror Concept

- Closed Loop Active Surface
- Bolted Steel Truss
  - CFRP possible if low cost
- 7 Rings of Panels
  - 210 Panels @ 1.7 m
- 3 Actuators per Panel
  - Kinematic bipod flexures
Primary Mirror Panels

- Possible Panel Techs.
  - CFRP/Al Sandwich
  - Lightweight Borosilicate
  - Ni/Al Sandwich
  - Al/Al Sandwich
- \( \sim 8 \text{ kg m}^{-2} \) Areal Density
- \( \sim 5 \mu m \text{ rms Total Error} \)

Total Gravity Distortion \( \sim 2 \mu m \text{ rms} \)
Active Surface Alignment

- **Sensing and Control Model**
  - D. MacDonald, D. Woody, JPL
  - Sensor response to segment motions, modal analysis
  - Closed loop control to maintain surface
  - Low sensor sensitivity to global modes, i.e., focus, tilts
  - Thermal and gravity segment distortions disrupt control

- **“Edge” Sensors**
  - Displacement and dihedral information at segment borders
  - Necessary but not sufficient
  - Fogale Nanotech inductive designs
CCAT $f = 0.4$ Mirror Modes

Displacement sensors on 55 mm fingers
Segment Tilt Sensor

- Optical system measures segment tilts
- Complements edge sensors
- Improves mirror control
- Concept design by Adaptive Optics Associates
Surface Alignment Calibration

- Initial Panel Alignment
  - Optomechanical
  - Photogrammetry
- Submm Interferometry
  - Uses Distant Planets
    - Mars, Uranus, & Neptune
  - Three Techniques Proposed
    - Shearing with Single Detector
    - Shearing with Extended FPA
    - Point Diffraction Interferometer
  - Single Detector Used at CSO
  - Arrays Improve Systematics?

Hybrid Interferometer Combines Three Types in One Instrument

G. Serabyn, JPL
CCAT Instruments

• Direct Illumination Cameras
  – SCUBA2: 450 & 850 μm
  – SWCam: 200–620 μm
• Antenna Coupled Camera
  – LWCam: 700–2000 μm
• Spectrometers
  – Multiobject gratings
• Heterodyne Receivers
  – Array cameras
  – ALMA receiver, connect to ALMA, VLBI
• Legacy Instrumentation
Direct Illumination Cameras

- **SCUBA2 (UK ATC, Canada)**
  - To JCMT in 2007
  - On CCAT, would be:
    - Proven first light instrument
    - 2.7' at 450 μm, 5' at 850 μm

- **CCAT SW Camera (concept)**
  - 200 μm, 350 μm, 450 μm, 620 μm
  - Single color with filter wheel
  - NIST TES silicon bolometers
  - Total: 32 000 pixels
  - 5' field of view @ 350 μm
Antenna Coupled MKID Camera

- CSO camera (CIT, Colorado)
  - DemoCam, 4x4 pixels, two colors
  - CSO observations in 2007 April
  - Successor funded, NSF ATI
  - 24x24 pix, 4 color 750-1300 μm

- CCAT LW Camera (concept)
  - 750–2000 μm, 45 000 pixels
  - Up to 20' x 20' Field of View
Spectrometers

- **Zeus (Cornell)**
  - Long slit echelle grating
  - 350, 450, 610 μm, R ~ 1000
  - Already to CSO

- **Z-Spec (CIT, JPL, Colorado)**
  - Parallel plate grating cavity
  - 190–310 GHz, R ~ 250 to 400
  - Already to CSO (2005 June)

- **Multiobject**
  - Flexible dielectric waveguide
  - Optical relays
  - Laboratory studies
Heterodyne Receivers

- **Super Cam (Arizona)**
  - 64 pixels, 330–360 GHz
  - FPGA spectrometers
  - 1 GHz IF BW
  - Under development

- **CHARM (concept)**
  - 64–128 pixels, 650–700 GHz
  - 2–4 GHz IF BW
  - Digital spectrometers

- **ALMA Receivers**
  - Anchor for long baselines
  - At 350 μm, add 14% sens.
  - Improve dirty sidelobe levels
    - 9% ⇒ 7% (Holdaway)
  - Also VLBI
Consortium

- Caltech
  - Includes JPL involvement
- Cornell University
- University of Colorado Boulder
- UK Astronomy Technology Centre (STFC)
- Canada (Univs. of BC & Waterloo)
- Other Institutions Interested

Interim Consortium Agreement Signed in 2007
Full Project Agreement Planned in 2008
Project Phases and Schedule

- **Feasibility/Concept Design Study**
  - 2004 – 2006
  - Cornell, Caltech, & JPL: Develop Baseline Concept, Assess Feasibility, Initial Cost Estimate

- **Consortium Development Phase**
  - 2006 – 2008
  - Complete Consortium, Identify & Secure Funding
  - Address Key Technical Issues

- **Technical Development Phase**
  - 2008 – 2011
  - Detailed Design, Manufacture, Integration

- **Commissioning Phase**
  - 2012
  - Optimize Performance & Handover to Operations
“The CCAT will revolutionize Astronomy in the submm/FIR band and enable significant progress in unraveling the cosmic origin of stars, planets and galaxies. CCAT is very timely and cannot wait.”

From CAAT Design Review Committee Report (Robert W. Wilson, Chair)